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x3=2cosxCx1=2sinxC 3 4 x1=2cosx x1=2sinx 1 2 x1=2cosxCx3=2cosx 1 4 x1=2cosx C4xC x2. 1 4 .4xC8/D 4x3C8x2C 3x 2. 1.2.4. (a) If y0D xex, thenyD xexC R exdxCcD .1 x/exCc, and y.0/D 1) 1D 1Cc, so cD 0and yD .1 x/ex. (b) If y0D xsinx2, then y D 1 2 cosx2C c; y r ˇ 2 D 1) 1 D 0C c, so c D 1and yD 1 1 2 cosx2.

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r2(u2)θθ,0<r<1,0 ≤θ<2π,t>0, u2(1,θ,t)= 0,0 ≤θ<2π,t>0, u2(r,θ,0) = −u1(r,θ),0<r<1,0 ≤θ<2π. You can check, using linearity (or superposition), that. u(r,θ,t)=u1(r,θ)+u2(r,θ,t) is a solution of the given problem. The solution of subproblem #1 follows immediately from the method of Sec- tion 4.5. We have.

Students Solutions Manual PARTIAL DIFFERENTIAL EQUATIONS

- Find a linear second-order differential equation F(x, y, y, y) 0 for which y c1x c2x2 is a twoparameter family of solutions. Make sure that your equation is free of the arbitrary parameters c1 and c2. Qualitative information about a solution y (x) of a differential equation can often be obtained from the equation itself. Before working Problems 55

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